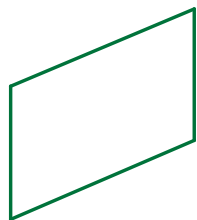
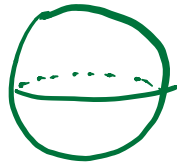


§ Surfaces in \mathbb{R}^3

Q: Which one do we want to consider as "surfaces"?



plane

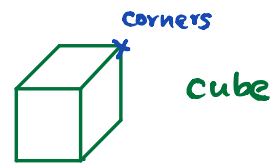


sphere

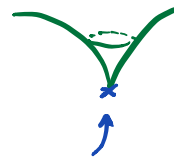


torus

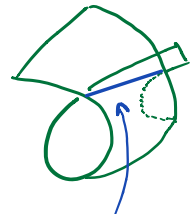
YES



cube



cusp



self-intersection

NO

Basic idea: A "surface" is an object that ^① locally
^② looks like a piece of \mathbb{R}^2 .

Definition: A (regular) surface is a subset

$$S \subseteq \mathbb{R}^3$$

s.t. $\forall p \in S, \exists$ nbd. of p (in S) $V \subseteq S$

and a smooth map (called parametrization / chart)


$$\chi : \mathcal{U} \subseteq \mathbb{R}^2 \xrightarrow{\text{open}} V$$

s.t. (1) $\chi : \mathcal{U} \rightarrow V$ is a homeomorphism.

* (2) The differential $d\chi|_q$ is 1-1 $\forall q \in \mathcal{U}$.

Explanation on * : More explicitly,

$$\Sigma(u,v) = (x(u,v), y(u,v), z(u,v)) \quad , \quad q = (u,v) \in \mathcal{U}$$



smooth functions

The differential of Σ at $q \in \mathcal{U}$ is a linear map

$$d\Sigma|_q : \mathbb{R}^2 \rightarrow \mathbb{R}^3$$

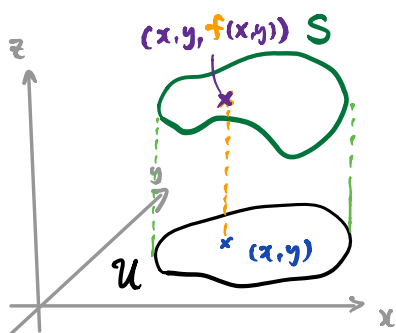
which can be expressed in matrix form (w.r.t. std basis)

$$d\Sigma|_q = \begin{pmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} \end{pmatrix} \Big|_q =: \begin{pmatrix} | & | \\ \frac{\partial \Sigma}{\partial u} & \frac{\partial \Sigma}{\partial v} \\ | & | \end{pmatrix} \Big|_q$$

$$d\Sigma|_q \text{ is 1-1} \iff \frac{\partial \Sigma}{\partial u}, \frac{\partial \Sigma}{\partial v} \text{ are linearly independent.}$$

Example 1 : Graphical surfaces

Given a smooth function $f : \mathcal{U} \subset \mathbb{R}^2 \rightarrow \mathbb{R}$



$$\begin{aligned} S &= \text{graph}(f) \\ &= \{ z = f(x,y) \mid (x,y) \in \mathcal{U} \} \\ &\text{is a (regular) surface.} \end{aligned}$$

Why? Consider the smooth map

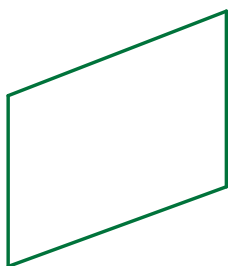
$$\begin{array}{ccc} \mathbb{X} : \mathcal{U} \in \mathbb{R}^2 & \longrightarrow & \mathbb{S} \in \mathbb{R}^3 \\ \downarrow & & \downarrow \\ (u, v) & \longmapsto & (u, v, f(u, v)) \end{array}$$

Clearly, $\mathbb{X} : \mathcal{U} \rightarrow \mathbb{S}$ is a homeomorphism.

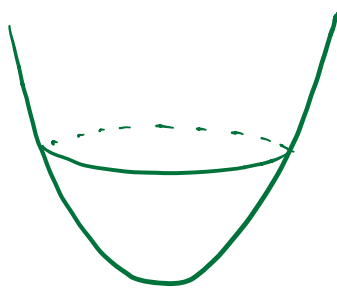
$$\left. \begin{array}{l} \frac{\partial \mathbb{X}}{\partial u} = \left(1, 0, \frac{\partial f}{\partial u} \right) \\ \frac{\partial \mathbb{X}}{\partial v} = \left(0, 1, \frac{\partial f}{\partial v} \right) \end{array} \right\} \text{always linearly independent.}$$

Examples of graphical surfaces

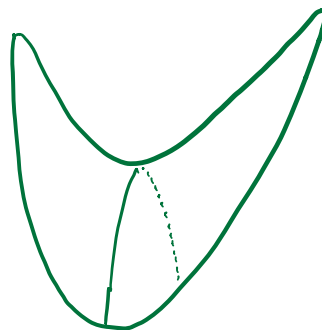
- $f(x, y) = ax + by + c \implies$ planes
- $f(x, y) = x^2 + y^2 \implies$ paraboloid
- $f(x, y) = x^2 - y^2 \implies$ hyperboloid



plane



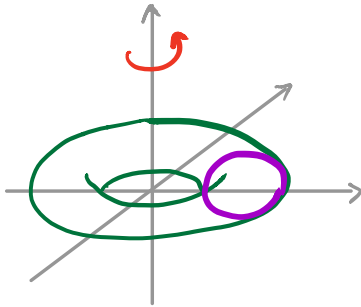
paraboloid



hyperboloid

Note: The entire surface can be covered by 1 chart.

Example 2 : Torus of revolution



$$S = \{ (\sqrt{x^2+y^2} - a)^2 + z^2 = r^2 \}$$

where $a > r > 0$ are constants.

is a surface.

Exercise: Prove this.

How many parametrizations do we need to cover the whole torus?